STIM300 offers several user selectable output formats and sample rates for gyro and accelerometer data:

- Angular Rate
- Incremental Angle
- Average Angular Rate
- Integrated Angle
- Acceleration
- Incremental Velocity
- Average Acceleration

Device configurations and self-diagnostics

A reliable RISC ARM microcontroller enables easy device configuration and programming. The user selectable Service Mode allows for setting the output unit format, sample frequency, LP filter cut-off frequency, RS422 transmission bit rate and line termination. Service Mode also enables single measurements on demand, and to access detailed diagnostics information.

Evaluation tools

STIM300 evaluation tools supporting PCI or USB connectivity are available. The evaluation tools offer easy access to measurement data and configuration of the IMU. It supports data sampling at alternative rates, graphical presentation, and data logging to file. The evaluation tools contain a RS422 interface for USB or PCI hardware setup, all necessary cabling, and PC software.

Application areas

The STIM300 IMU is well suited for stabilization, guidance and navigation applications in Industrial, Aerospace and Defense markets. It is a crucial building block for inertial navigation systems in UAVs, AUVs, AGVs, UGVs and ROVs, robotics, and more, and offers the designer an ITAR free alternative. In many applications, STIM300 can competitively replace IMU’s based on Fiber Optic Gyros (FOGs) and improve system performance with respect to robustness, reliability, size, weight, power and cost.
**Parameter** | Min | Nom | Max | Unit | Description
--- | --- | --- | --- | --- | ---
**GENERAL** |  |  |  |  |  
Weight | 55 | 85 | g |  
Operating temperature | -40 | 85 | °C |  
Supply voltage | 4.5 | 5.0 | 5.5 | V |  
Power consumption | 1.5 | 2 | W |  
Start-up time | 3 | s |  |  
Sample rate | 2000 | SPS |  |  
Mechanical shock, any direction | 1500 | g |  |  
RS422 transmission bit rate | 5.18 |  | Mbits/s |  
Misalignment | 1 | mrad |  |  
**GYRO** |  |  |  |  |  
Input range | ±10  | g |  |  
Non-linearity (condition: ±200 °/s) | 15 | ppm |  |  
Resolution | 0.22 | °/h |  |  
Bias instability | 0.3 | °/h |  |  
Angular random walk | 0.15 | °/Vh |  |  
Bias error over temperature gradients | ±10  | °/h rms |  |  
Linear acceleration effect | Bias | 1  | °/h/g |  
Scale factor | 50  | ppm/g |  |  
Scale factor accuracy | ±500 | ppm |  |  
**ACCELEROMETER** |  |  |  |  |  
Input range | ±10  | °/s |  |  
Resolution | 1.9 | µg |  |  
Bias instability | 0.05 | mg |  |  
Velocity random walk | 0.07 | m/s/Vh |  |  
Bias error over temperature gradients | ±2  | mg rms |  |  
Scale factor accuracy | ±300 | ppm |  |  
**INCLINOMETER** |  |  |  |  |  
Input range | ±1.7 | g |  |  
Resolution | 0.2 | µg |  |  
Scale factor accuracy | ±500 | ppm |  |  
**MECHANICAL DIMENSIONS** |  |  |  |  |  
All dimensions in mm. Volume < 2.0 cu. in (33 cm³) |  |  |  |  |  

1) Optional ranges are available  
2) Condition: ΔT ≤ 1°C/min  
3) Optional ranges: ±5 g, ±30 g, ±80 g  
4) With g compensation  

**FUNCTIONAL BLOCK DIAGRAM**

**ELECTRICAL CONNECTIONS**

**PIN OUT**

**AXIS DEFINITIONS**

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